

A Generalization of the Concept of Functions (III)

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1. Introduction

In the previous papers [2] and [3], we have introduced a concept of generalized functions. Our definition is as follows:

DEFINITION 1.1. Let $R^+ = \{y \in R; y > 0\}$, and let $F = \{(0, y); y \in R^+\}$. Then F has the finite intersection property. We shall denote with \mathcal{F} the ultrafilter generated by F . Let $a(y), b(y) \in \prod_{y \in R^+} \text{Map}(R^n, C)$. Define $a(y) \sim b(y)$ if the following condition is satisfied:

$$\{y \in R^+; a(y) = b(y)\} \in \mathcal{F}.$$

It is easy to see that this relation is an equivalence relation. Define

$$*\text{Map}(R^n, C) = \prod_{y \in R^+} \text{Map}(R^n, C) / \sim.$$

The equivalence class determined by a function $a(y) \in \prod_{y \in R^+} \text{Map}(R^n, C)$ will be denoted by $[a(y)]$. An element of the space $*\text{Map}(R^n, C)$ is called a generalized function (G-function).

Similarly we can define spaces $**\text{Map}(R^n, C) = (*\text{Map}(R^n, C))$, $***\text{Map}(R^n, C) = (**\text{Map}(R^n, C))$, ...

In the present paper we intend to give another definition of generalized functions. Using the definition we would like to show that the spaces $**\text{Map}(R^n, C)$, $***\text{Map}(R^n, C)$, ..., are given by direct generalization of the space $\text{Map}(R^n, C)$.

2. Preliminaries and Several Properties

We shall first give the following definition (see Comfort and Negrepointis [1]):

DEFINITION 2.1. Let \mathcal{F} be the ultrafilter defined in Definition 1.1. Define

$$(2.1) \quad \mathcal{F} \cdot \mathcal{F} = \{A \in \mathcal{P}(R^+ \times R^+); \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in A\} \in \mathcal{F}\} \in \mathcal{F}\},$$

$$(2.2) \quad (\mathcal{F} \cdot \mathcal{F}) \cdot \mathcal{F} = \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \{y_3 \in R^+; \{(y_1, y_2) \in R^+ \times R^+; (y_1, y_2, y_3) \in A\} \in \mathcal{F} \cdot \mathcal{F}\} \in \mathcal{F}\},$$

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- (2.3) $\mathcal{F} \cdot \mathcal{F} \cdot \mathcal{F} = \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \{y_3 \in R^+; \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2, y_3) \in A\} \in \mathcal{F}\} \in \mathcal{F}\} \in \mathcal{F}\},$
- (2.4) $\mathcal{F} \times \mathcal{F} = \{A \in \mathcal{P}(R^+ \times R^+); \text{there are } B, C \in \mathcal{F} \text{ such that } B \times C \subset A\},$
- (2.5) $(\mathcal{F} \times \mathcal{F}) \times \mathcal{F} = \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \text{there are } B \in \mathcal{F} \times \mathcal{F}, C \in \mathcal{F} \text{ such that } B \times C \subset A, \text{ and}\}$
- (2.6) $\mathcal{F} \times \mathcal{F} \times \mathcal{F} = \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \text{there are } B, C, D \in \mathcal{F} \text{ such that } B \times C \times D \subset A\}.$

We have the following lemma:

- LEMMA 2.2. (i) $\mathcal{F} \cdot \mathcal{F}$ is an ultrafilter on $\mathcal{P}(R^+ \times R^+)$,
(ii) $\mathcal{F} \times \mathcal{F}$ is a filter on $\mathcal{P}(R^+ \times R^+)$ and we have $\mathcal{F} \times \mathcal{F} \subset \mathcal{F} \cdot \mathcal{F}$,
(iii) $(\mathcal{F} \cdot \mathcal{F}) \cdot \mathcal{F}$ is an ultrafilter on $\mathcal{P}(R^+ \times R^+ \times R^+)$,
(iv) In the same way as (2.2) we can define $\mathcal{F} \cdot (\mathcal{F} \cdot \mathcal{F})$ and we have

$$(\mathcal{F} \cdot \mathcal{F}) \cdot \mathcal{F} = \mathcal{F} \cdot \mathcal{F} \cdot \mathcal{F} = \mathcal{F} \cdot (\mathcal{F} \cdot \mathcal{F}),$$

- (v) $(\mathcal{F} \times \mathcal{F}) \times \mathcal{F}$ is a filter on $\mathcal{P}(R^+ \times R^+ \times R^+)$ and we have

$$(\mathcal{F} \times \mathcal{F}) \times \mathcal{F} \subset (\mathcal{F} \cdot \mathcal{F}) \cdot \mathcal{F}, \text{ and}$$

- (vi) In the same way as (2.5) we can define $\mathcal{F} \times (\mathcal{F} \times \mathcal{F})$ and we have

$$(\mathcal{F} \times \mathcal{F}) \times \mathcal{F} = \mathcal{F} \times \mathcal{F} \times \mathcal{F} = \mathcal{F} \times (\mathcal{F} \times \mathcal{F}).$$

PROOF. We shall only prove (i), (ii) and (iv).

- (i) 1° It is clear that $\phi \notin \mathcal{F} \cdot \mathcal{F}$.

- 2° Let $A \in \mathcal{F} \cdot \mathcal{F}$ and $A \subset B$. Since

$$\{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in A\} \in \mathcal{F}\} \subset \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in B\} \in \mathcal{F}\} \text{ and}$$

$$\{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in A\} \in \mathcal{F}\} \in \mathcal{F},$$

we have $\{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in B\} \in \mathcal{F}\} \in \mathcal{F}$ and therefore $B \in \mathcal{F} \cdot \mathcal{F}$.

- 3° Let $A, B \in \mathcal{F} \cdot \mathcal{F}$. Since

$$\{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in A \cap B\} \in \mathcal{F}\}$$

$$= \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in A\} \in \mathcal{F}\} \cap \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in B\} \in \mathcal{F}\},$$

we have

$$\{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in A \cap B\} \in \mathcal{F}\} \in \mathcal{F},$$

$$A \cap B \in \mathcal{F} \cdot \mathcal{F}.$$

- 4° Let $A \in \mathcal{P}(R^+ \times R^+)$ and $A \notin \mathcal{F} \cdot \mathcal{F}$. Define

$$T_{y_2} = \{y_1 \in R^+; (y_1, y_2) \in A\} \text{ for } y_2 \in R^+, \text{ and}$$

$$S = \{y_2 \in R^+; T_{y_2} \in \mathcal{F}\}.$$

Then $S \in \mathcal{F}$ and hence $R^+ - S \in \mathcal{F}$. Since

$$R^+ - S = \{y_2 \in R^+; T_{y_2} \notin \mathcal{F}\}, \text{ and}$$

$$T_{y_2} \notin \mathcal{F} \Leftrightarrow \{y_1 \in R^+; (y_1, y_2) \in R^+ \times R^+ - A\} \in \mathcal{F}.$$

we have

$$R^+ - S = \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in R^+ \times R^+ - A\} \in \mathcal{F}\} \in \mathcal{F},$$

and hence

$$R^+ \times R^+ - A = A^c \in \mathcal{F} \cdot \mathcal{F}.$$

We have therefore proved (i).

(ii) 1° It is clear that $\phi \in \mathcal{F} \times \mathcal{F}$.

2° Let $A \in \mathcal{F} \times \mathcal{F}$ and $A \subset A_0$. There are $B_1, C_1 \in \mathcal{F}$ such that $B_1 \times C_1 \subset A$. Thus we have $B_1 \times C_1 \subset A_0$, and therefore $A_0 \in \mathcal{F} \cdot \mathcal{F}$.

3° Let $A_1, A_2 \in \mathcal{F} \times \mathcal{F}$. There are $B_1, B_2, C_1, C_2 \in \mathcal{F}$ such that $B_1 \times C_1 \subset A_1$ and $B_2 \times C_2 \subset A_2$. Since

$$(B_1 \cap B_2) \times (C_1 \cap C_2) \subset A_1 \cap A_2 \text{ and } B_1 \cap B_2, C_1 \cap C_2 \in \mathcal{F},$$

we have $A_1 \cap A_2 \in \mathcal{F} \times \mathcal{F}$.

4° Let $A \in \mathcal{F} \times \mathcal{F}$. There are $B, C \in \mathcal{F}$ such that $B \times C \subset A$. Since $\{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2) \in B \times C\} \in \mathcal{F}\} \in \mathcal{F}$ we have $B \times C \in \mathcal{F} \cdot \mathcal{F}$ and hence $A \in \mathcal{F} \cdot \mathcal{F}$. We have therefore proved (ii).

(iv) Since

$$\begin{aligned} & \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \{y_3 \in R^+; \{(y_1, y_2) \in R^+ \times R^+; (y_1, y_2, y_3) \in A\} \in \mathcal{F} \cdot \mathcal{F}\} \in \mathcal{F}\} \\ &= \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \{y_3 \in R^+; \{y_2 \in R^+; \{y_1 \in R^+; (y_1, y_2, y_3) \in A\} \in \mathcal{F}\} \\ &\in \mathcal{F}\} \in \mathcal{F}\} \\ &= \{A \in \mathcal{P}(R^+ \times R^+ \times R^+); \{(y_2, y_3) \in R^+ \times R^+; \{y_1 \in R^+; (y_1, y_2, y_3) \in A\} \in \mathcal{F}\} \\ &\in \mathcal{F} \cdot \mathcal{F}\} \end{aligned}$$

we have

$$(\mathcal{F} \cdot \mathcal{F}) \cdot \mathcal{F} = \mathcal{F} \cdot \mathcal{F} \cdot \mathcal{F} = \mathcal{F} \cdot (\mathcal{F} \cdot \mathcal{F}).$$

DEFINITION 2.3. Let $K \neq \phi$, and let $a(y_1, y_2), b(y_1, y_2) \in \prod_{(y_1, y_2) \in R^+ \times R^+} K$. Define $a(y_1, y_2) \sim 2 b(y_1, y_2)$ if the following condition is satisfied:

$$\{(y_1, y_2) \in R^+ \times R^+; a(y_1, y_2) = b(y_1, y_2)\} \in \mathcal{F} \cdot \mathcal{F}.$$

It is easy to see that this relation ~ 2 is an equivalence relation. Define

$$(*2)K = \prod_{(y_1, y_2) \in R^+ \times R^+} K / \sim 2.$$

The equivalence class determined by $a(y_1, y_2)$ will be denoted with $[a(y_1, y_2)]$.

THEOREM 2.4. $**K = (*2)K$.

PROOF. If $(a(y_1))(y_2) \in \prod_{y_2 \in R^+} (\prod_{y_1 \in R^+} K)$, then we consider $(a(y_1))(y_2) \in \prod_{(y_1, y_2) \in R^+ \times R^+} K$, and write $(a(y_1))(y_2) = a(y_1, y_2)$. Let $[[a(y_1)](y_2)], [[b(y_1)](y_2)] \in **K$. Since

$$\begin{aligned} [[a(y_1)](y_2)] &= [[b(y_1)](y_2)] \\ &\Leftrightarrow \{y_2 \in R^+; [a(y_1)](y_2) = [b(y_1)](y_2)\} \in \mathcal{F} \\ &\Leftrightarrow \{y_2 \in R^+; \{y_1 \in R^+; (a(y_1))(y_2) = (b(y_1))(y_2)\} \in \mathcal{F}\} \in \mathcal{F} \\ &\Leftrightarrow \{(y_1, y_2) \in R^+ \times R^+; a(y_1, y_2) = b(y_1, y_2)\} \in \mathcal{F} \cdot \mathcal{F} \\ &\Leftrightarrow [a(y_1, y_2)] = [b(y_1, y_2)], \end{aligned}$$

we immediately have $**K = (*2)K$.

COROLLARY 2.5. $**\text{Map}(R^n, C) = (*2)\text{Map}(R^n, C)$.

DEFINITION 2.6. Let $K \neq \phi$, and let $a(y_1, y_2, y_3), b(y_1, y_2, y_3) \in \prod_{(y_1, y_2, y_3) \in R^+ \times R^+ \times R^+} K$. Define $a(y_1, y_2, y_3) \sim 3 b(y_1, y_2, y_3)$ if the following condition is satisfied:

$$\{(y_1, y_2, y_3) \in R^+ \times R^+ \times R^+; a(y_1, y_2, y_3) = b(y_1, y_2, y_3)\} \in \mathcal{F} \cdot \mathcal{F} \cdot \mathcal{F}.$$

It is easy to see that this relation ~ 3 is an equivalence relation. Define

$$(*3)K = \prod_{(y_1, y_2, y_3) \in R^+ \times R^+ \times R^+} K / \sim 3.$$

The equivalence class determined by a function $a(y_1, y_2, y_3)$ will be denoted by $[a(y_1, y_2, y_3)]$.

THEOREM 2.7. Let $K \neq \phi$. Then

$$(2.7) \quad (*3)K = *(*)K = (*2)*K = ***K.$$

PROOF. Since

$$\begin{aligned} \prod_{(y_1, y_2, y_3) \in R^+ \times R^+ \times R^+} K / \sim 3 &= \prod_{y_3 \in R^+} \left(\prod_{(y_1, y_2) \in R^+ \times R^+} K / \sim 2 \right) / \sim \\ &= \prod_{(y_2, y_3) \in R^+ \times R^+} \left(\prod_{y_1 \in R^+} K / \sim \right) / \sim 2 \\ &= \prod_{y_3 \in R^+} \left(\prod_{y_2 \in R^+} \left(\prod_{y_1 \in R^+} K / \sim \right) / \sim \right) / \sim, \end{aligned}$$

we immediately have (2.7).

COROLLARY 2.8. $(^{*3})\text{Map}(R^n, C) = (^{*2})^*\text{Map}(R^n, C)$
 $= (^{*2})^*\text{Map}(R^n, C) = \dots = (^{*n})\text{Map}(R^n, C).$

We can generalize Theorem 2.7 and Corollary 2.8 as follows:

THEOREM 2.9. Let $K \neq \phi$. Then

$$(^{*d})K = (^{*(d-1)})K = \dots = (^{*n})K.$$

COROLLARY 2.10. $(^{*d})\text{Map}(R^n, C) = (^{*(d-1)})\text{Map}(R^n, C) = \dots = (^{*n})\text{Map}(R^n, C).$

EXAMPLE 2.11. Let

$$\begin{aligned} & [\delta(x_1, \dots, x_n, y_1, \dots, y_n)] \\ &= \left[\frac{1}{(2\pi i)^n} \left(\frac{1}{x_1 - iy_1} - \frac{1}{x_1 + iy_1} \right) \dots \left(\frac{1}{x_n - iy_n} - \frac{1}{x_n + iy_n} \right) \right] \\ &= \left[\frac{1}{\pi^n} \cdot \frac{y_1}{x_1^2 + y_1^2} \dots \frac{y_n}{x_n^2 + y_n^2} \right] \quad \text{for } x_1, \dots, x_n \in R \text{ and } y_1, \dots, y_n \in R^+. \end{aligned}$$

Then $[\delta(x_1, \dots, x_n, y_1, \dots, y_n)]$ is a delta function of n -variables and $[\delta(x_1, \dots, x_n, y_1, \dots, y_n)] \in (^{*n})\text{Map}(R^n, C).$

References

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